







- * Sherdil Niyaz, Senior in EECS
- * Discussion: 1-2 W in 3113 Etch
- * Hopefully another section if we expand the course
- * Office hours: 1-3pm on Friday in 341A Soda (In Upper Division Lounge)
- * Interests: Teaching, Robotics, CS Theory, Al



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- Feeling lost in the class? Falling behind? Just want to talk about the course (or anything?) Don't be afraid to email!
- * Also, please bug me if I don't respond. I don't mind.



http://sniyaz.weebly.com/cs188.html

* Pon't feel pressured to take notes. I will put up anything I use on this site.

* Instead, I want you listening in section and not rushing to write things down :)

Rules of Section

- Be respectful. Don't be condescending to people who take longer to really master a topic.
- * Pon't be afraid to ask questions. The only stupid question is the one you don't ask.
- * If I don't address you using your name, call me out on it!
- * If I talk too fast, give me a signal to slow down.





- * Name! Year! Major! Social Security Number!
- * Share an interesting thing you've done, about you, etc. Just something interesting.
- * You may be asked to share....make sure you pay attention.

Anything interesting?

(Keep it PG-13 and legal please)

Things you should remember for this class

* CS61B: Graphs, Asymptotic Analysis



* Not comprehensive list

Now is a good time to review these if you've forgotten!





- * I'm at a START state. I want to reach an END state. How should I get there?
- There are actually multiple paradigms to solving problems like this. The first is a graph based approach.
- * There are others! (Game Trees, CSPs, Logic)





State representation

- Information needed to encode what your progress though the problem is.
- * Another way to think about it: what information do you store store to know which node in the graph you're at?
- Minimal State Representation: what is the smallest amount of information you can store to know which node in the graph you're at?

Transition function





* Graph analogy: each edge out of a state/ node represents an action. Which edges should exist between states and which shouldn't?



* Nodes = states



* Action can have costs.

* How do we solve? Just apply graph search algorithms from CS61B! (DFS, BFS...)

CS61B Fun Times

function GRAPH-SEARCH(*problem*, *fringe*) return a solution, or failure $closed \leftarrow an empty set$ $fringe \leftarrow \text{INSERT}(\text{MAKE-NODE}(\text{INITIAL-STATE}[problem]), fringe)$ loop do if *fringe* is empty **then return** failure $node \leftarrow \text{REMOVE-FRONT}(fringe)$ if GOAL-TEST(*problem*, STATE[*node*]) then return *node* if STATE[*node*] is not in *closed* then add STATE[*node*] to *closed* **for** *child-node* in EXPAND(STATE[*node*], *problem*) **do** $fringe \leftarrow \text{INSERT}(child-node, fringe)$ end end

How is Tree Search Different?

```
function GRAPH-SEARCH(problem, fringe) return a solution, or failure
closed \leftarrow an empty set
fringe \leftarrow \text{INSERT}(\text{MAKE-NODE}(\text{INITIAL-STATE}[problem]), fringe)
loop do
    if fringe is empty then return failure
    node \leftarrow \text{REMOVE-FRONT}(fringe)
    if GOAL-TEST(problem, STATE[node]) then return node
    if STATE[node] is not in closed then
        add STATE[node] to closed
        for child-node in EXPAND(STATE[node], problem) do
            fringe \leftarrow \text{INSERT}(child-node, fringe)
        end
end
```

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Ignore the Closed/Explored Set!





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This is the ONLY decision that changes the type of search!

PDB tutorial (if time allows)