

# Timing Sheet

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- 7: CSP Lecture
- 5: CSP Alone
- 5: CSP together
- 7: CSP Go Over
- 10: Game Tree lecture
- 6 Together (Or work in general)
- 7 Go Over Game Trees

# New Thing!

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**I want to make the 10 minutes before section a quick OH for conceptual questions. Don't be afraid to call me over and ask something!**

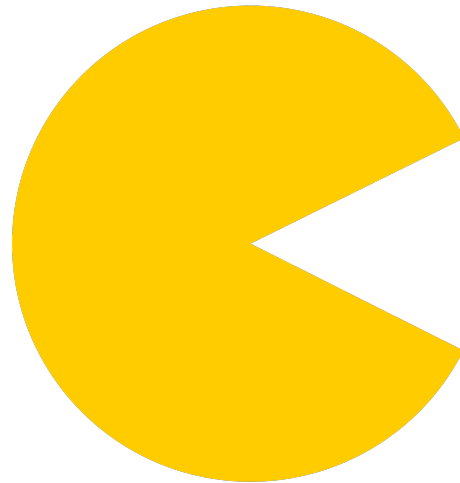
# CS 188: Artificial Intelligence

## Discussion 2:

### Constraint Satisfaction Problems and Game Trees

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# Administrivia

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- Project 1: Search

- Friday 9/16 at 5pm.
- Start early and ask questions. It's longer than most! There are extra credit "reach" objectives that are tough to beat.
- Solo or in group of two.

- Contest 1: Search

- Due Sunday 9/18 at 11:59pm.
- Solo or in group of two.
- Friendly competition. Consider joining in, even if you're not the competitive type.
- Extra credit opportunities if you beat the staff bots. Even more extra credit for top place finishers.

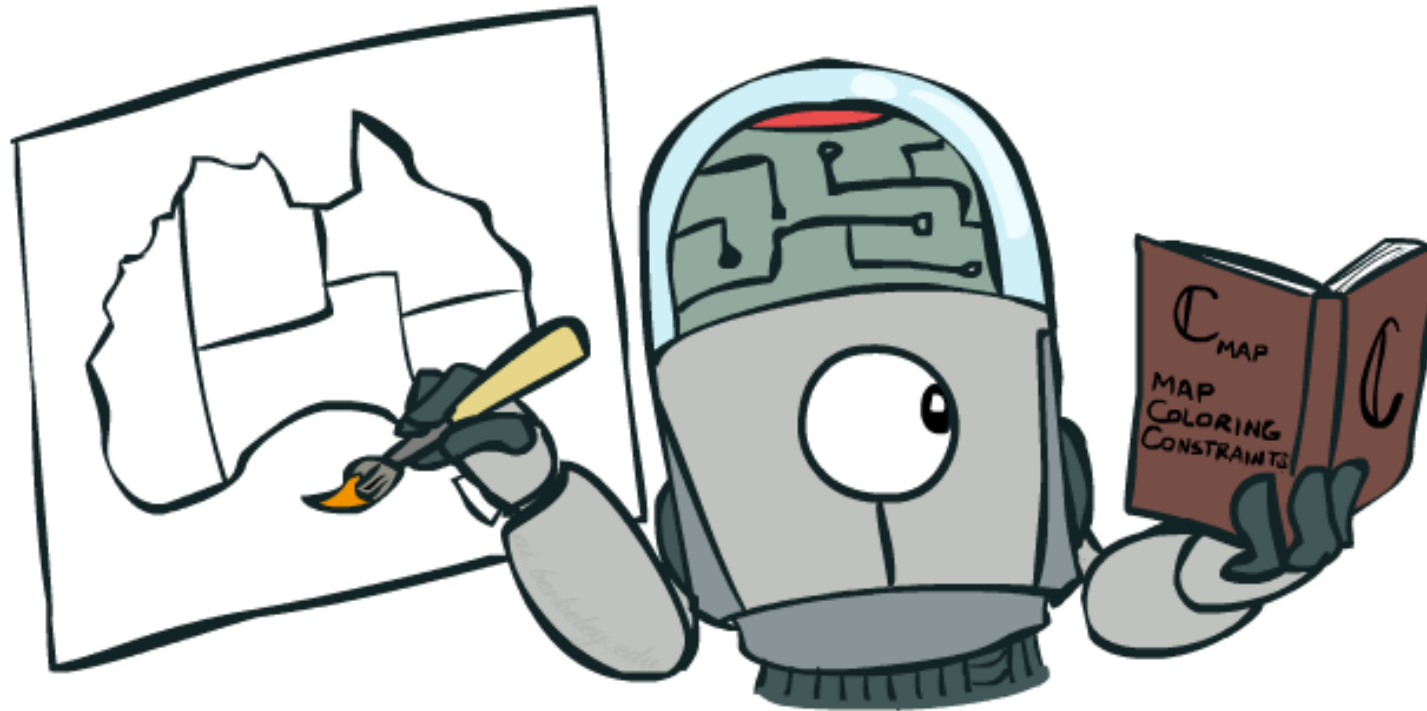
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Apologies if I have to squash questions at some point!

I will also probably (unconsciously) start talking fast since we have so much material. Please yell at me to slow down if I talk too fast!

**TODAY'S SECTION IS  
PACKED!**

# CSPs



# CSPs

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- Recall: Graph/Tree search
- Order mattered! Going  $A \rightarrow B \rightarrow C$  potentially different than  $C \rightarrow B \rightarrow A$ .
- CSPs are a special type of search problem where order of assignment **does not matter**.
- **Example:** I am scheduling classes. It does not matter whether I give CS61B a room before CS188, or CS188 a room before CS61B.

# Backtracking

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- With these problems where order doesn't matter, running DFS etc actually wastes lots of time.
- Alternative: Use the **backtracking algorithm!**
- Formulation: I have a bunch of **variables**, each with a **domain** of values I can assign to it.
- I also need to assign each variable with a value in its domain without violating any of the **constraints** that I'm given.



# TLDR: Backtracking

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- Keep assigning each variable a value in its domain that doesn't violate the given constraints
- When you can no longer do this and you haven't solved the CSP, you messed up!
- Time to **back track**: go to the last variable that you assigned a value, and give it a different one **if possible**. Try again.
- **Important**: May need to backtrack **multiple** times!

# Backtracking Power-Ups

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- **Common misconception from Office Hours:** Forward Checking, AC3, MRV, etc are **not** alternatives to Backtracking!
- Instead they are **power ups!** They are just extras that we strap onto backtracking to make it faster.
- **Forward checking:** When you assign a variable a value, kick out from its neighbors (aka variables that share a constraint with it) any conflicting values.
- **Arc Consistency (AC3)** is a stronger version of this.

# Moar Backtracking Power-Ups

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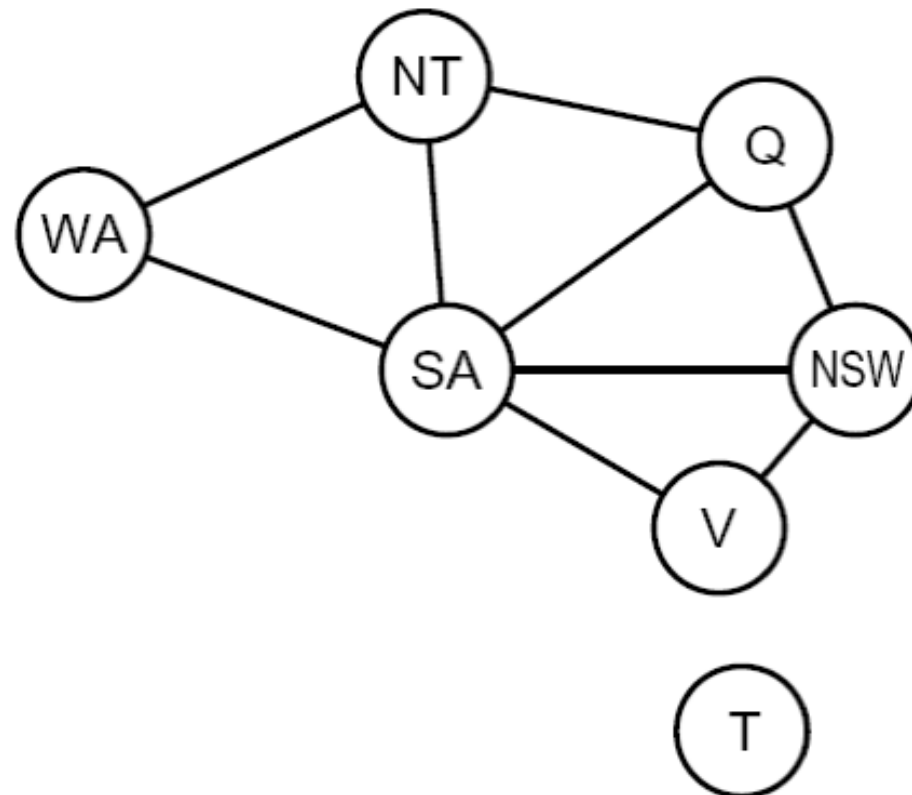
- **MRV:** When you pick the variable to assign next in backtracking, pick the one that has the minimum number of legal values left in its domain.
- **LCV:** Now that you've picked the next variable to assign, pick from its domain the **value** that would cause the **minimum** number of values to be ejected when forcing arc consistency.

# 3-Col Backtracking Animation!

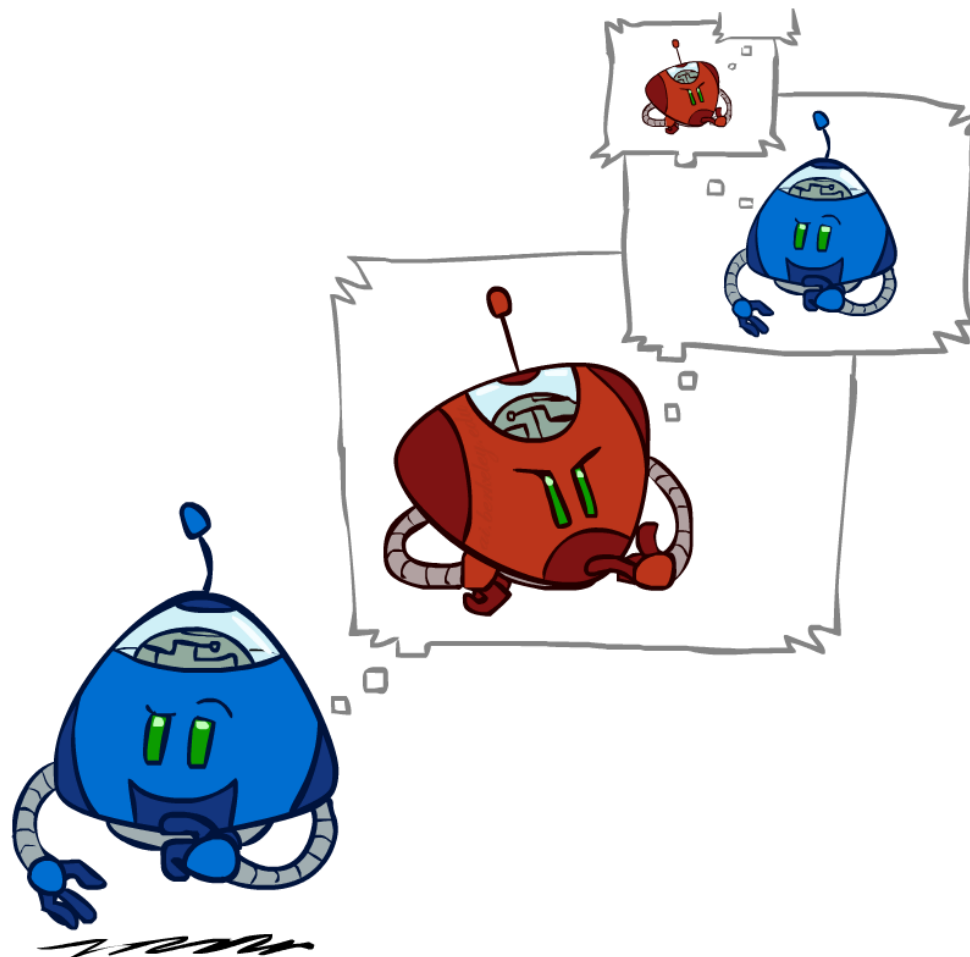
- This is on our section website, by the way!

<http://sniyaz.weebly.com/cs188.html>

- Note that this animation shows the **constraint graph**, where two variables share an edge if they are bound by a binary constraint.



# Game Trees



# Game Trees

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- **Notice:** In each of the search algorithms we've seen so far, there's only been **one** agent! (i.e. we've had Pacman, but no ghosts!)
- How do we handle **two** agents playing against each other?
- Let's assume that we have two players A and B playing a game **optimally**. A wants to maximize the score of the game, and B wants to minimize it.

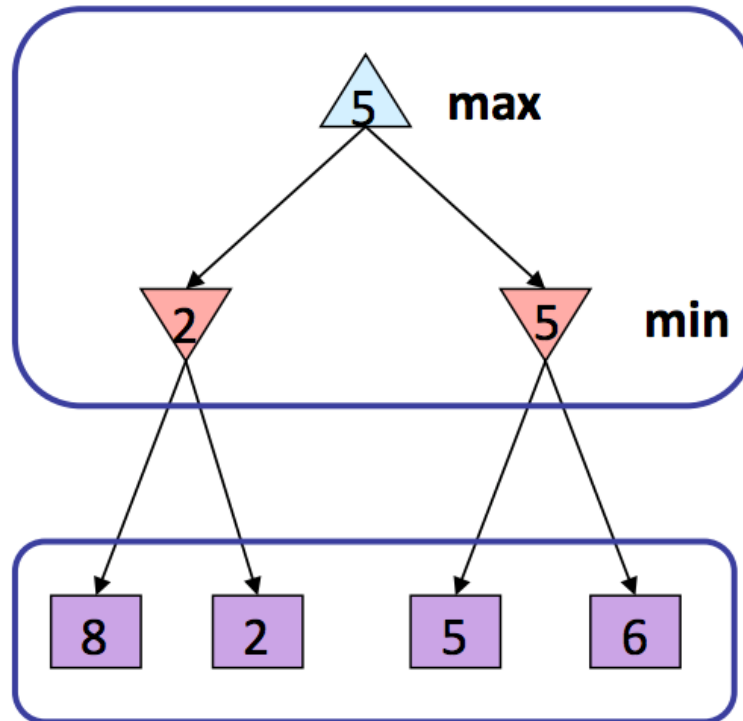
# Mini-Max Algorithm

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- Let's assume that we have two players A and B playing a game **optimally**. A wants to maximize the score of the game, and B wants to minimize it.
- We go from the **bottom** of the game tree up, and see which actions that each agent would take at each level.
- Remember, each branch in the game tree represents a different set of moves that might happen.

# Example

**Minimax values:  
computed recursively**



**Terminal values:  
part of the game**



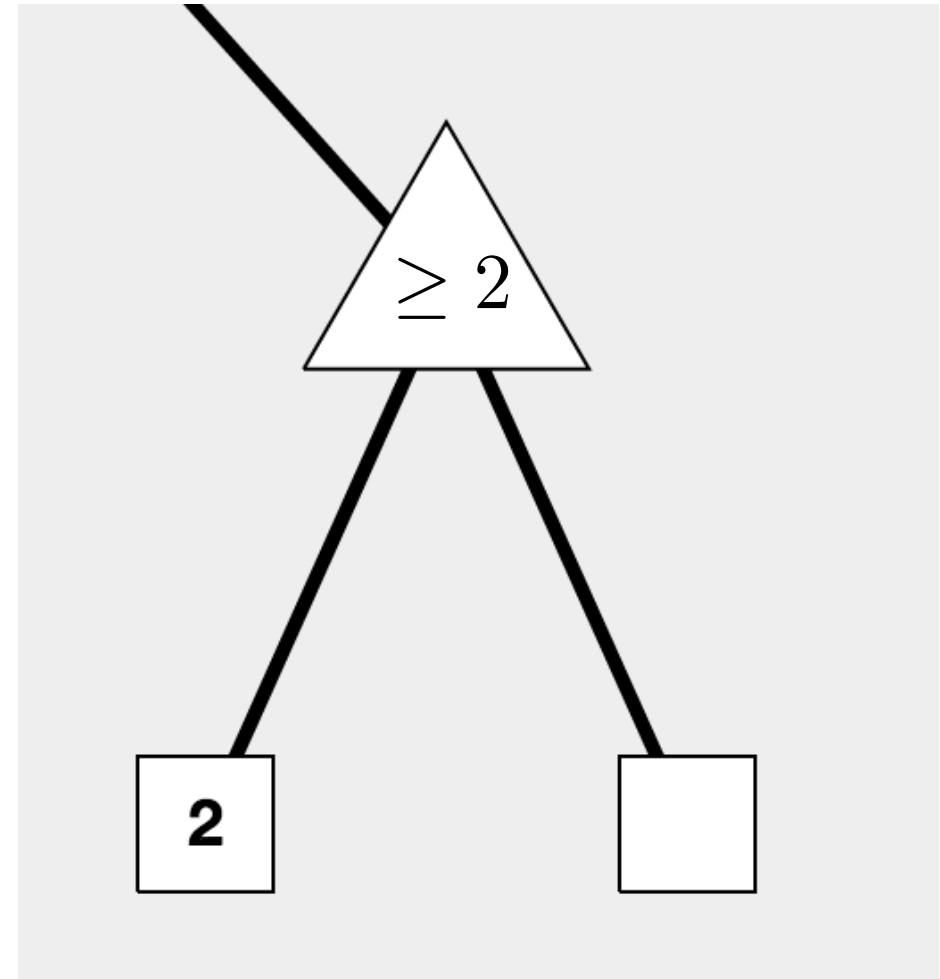
# Pruning

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- Sometimes certain parts of the game tree would never be reached since one of the players wouldn't allow it!
- When we know this is the case, we can stop computing on that branch and save time!
- Result: same answer, but faster runtime for Mini-Max

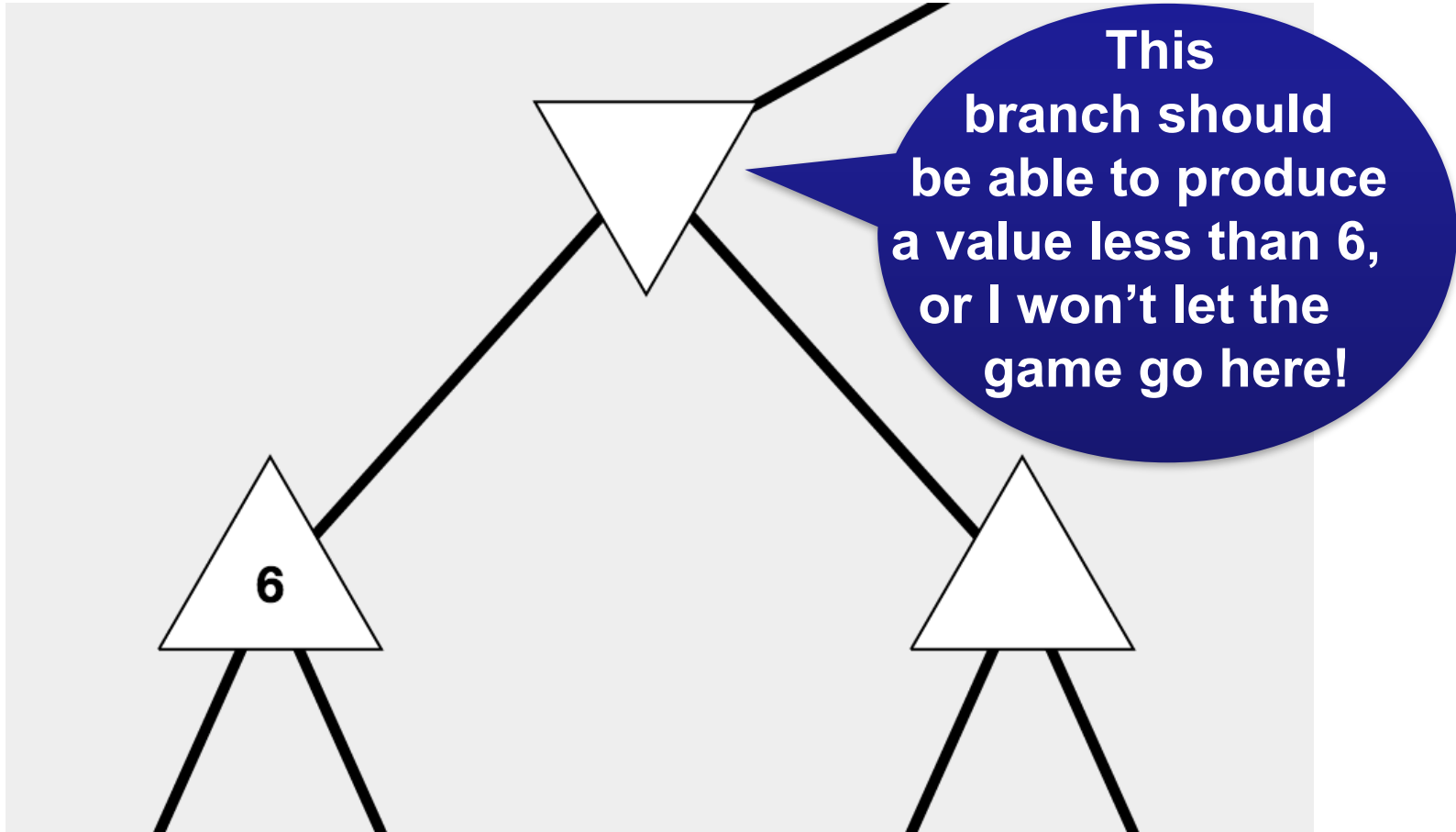
# Warm-Up 1: Bounds

- When a maximizer finds a value (2, in this case) the final value returned by the minimizer will be **at least** that value. (Since any choices that are smaller will get rejected).
- This is symmetric for a minimizer.



# Warm-Up 2: Allowing Branches

- If a minimizer has already found a value, they will only let the game proceed down branches that can find smaller values than the found one.
- This is symmetric for a maximizer.



# Pruning: A “cutoff” approach

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- Let's combine the previous two ideas!
- **Alphas and betas are confusing :/**  
I prefer to think in terms of cutoffs: If my “parent” node has found an option already, and I will only find things they like **less**, then why bother?
- Reasoning: they'll never let me even get to this point, since they play optimally. They can just force me to the option that's better for them.

# An example!

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- This is confusing! Show me an example?
  - [http://inst.eecs.berkeley.edu/~cs61b/fa14/ta-materials/apps/ab\\_tree\\_practice/](http://inst.eecs.berkeley.edu/~cs61b/fa14/ta-materials/apps/ab_tree_practice/)
- (Also linked from section site)
- This animation is awesome! Use it to generate infinite practice problems!